

Learn Physics by Programming in Haskell

Scott N. Walck
Department of Physics
Lebanon Valley College
Annville, Pennsylvania, USA

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Physics 261: Intro to Computational Physics

- ▶ Prereq: 1 year of intro physics, 1 semester of calculus
- ▶ No previous programming experience expected
- ▶ Goal is to deepen understanding of physics by expressing physics in a new language
- ▶ Spend about seven weeks learning a subset of Haskell
- ▶ Code for later parts of the course:
`cabal install learn-physics`

Types and higher-order functions help you learn physics

- ▶ expose the structure of Newtonian mechanics
- ▶ clarify and organize ideas in electromagnetic theory

A type for 3-dimensional vectors

```
data Vec = Vec { xComp :: Double
                 , yComp :: Double
                 , zComp :: Double
                 } deriving (Eq)
```

```
(^+^) :: Vec -> Vec -> Vec
```

```
Vec ax ay az ^+^ Vec bx by bz
  = Vec (ax+bx) (ay+by) (az+bz)
```

```
(*^) :: Double -> Vec -> Vec
```

```
c *^ Vec ax ay az = Vec (c*ax) (c*ay) (c*az)
```

Function types clarify our thinking

Function	Description	Type
(^+^)	vector addition	Vec -> Vec -> Vec
(^-^)	vector subtraction	Vec -> Vec -> Vec
(*^)	scalar multiplication	Double -> Vec -> Vec
(^*)	scalar multiplication	Vec -> Double -> Vec
(^/)	scalar division	Vec -> Double -> Vec
(<.>)	dot product	Vec -> Vec -> Double
(><)	cross product	Vec -> Vec -> Vec
magnitude	magnitude	Vec -> Double
zeroV	zero vector	Vec
iHat	unit vector	Vec
negateV	vector negation	Vec -> Vec
xComp	vector component	Vec -> Double
sumV	vector sum	[Vec] -> Vec

What could be simpler?

Newton's second law of motion says that
FORCE equals **MASS** times **ACCELERATION**


$$F=ma$$

Newton's Second Law is a Differential Equation

Even for a single object,

$$F = ma$$

is shorthand for

$$F_{\text{net}} \left(t, x, \frac{dx}{dt} \right) = m \frac{d^2x}{dt^2} \quad \text{in one dimension,}$$

or

$$\vec{F}_{\text{net}} \left(t, \vec{r}, \frac{d\vec{r}}{dt} \right) = m \frac{d^2\vec{r}}{dt^2} \quad \text{in three dimensions.}$$

For multiple particles, Newton's 2nd law is a set of coupled differential equations.

Euler Method for Newton's Second Law

The second-order differential equation

$$\frac{d^2\vec{r}}{dt^2} = \vec{a}\left(t, \vec{r}, \frac{d\vec{r}}{dt}\right)$$

has the following state update rule.

Over a short time Δt ,

$$(t, \vec{r}, \vec{v}) \rightarrow (t', \vec{r}', \vec{v}')$$

where

$$t' = t + \Delta t$$

$$\vec{r}' = \vec{r} + \vec{v}\Delta t$$

$$\vec{v}' = \vec{v} + \vec{a}(t, \vec{r}, \vec{v})\Delta t.$$

Mechanics of One Object in Three Dimensions

```
type Time          = Double
type Displacement = Vec
type Velocity      = Vec
type State         = (Time, Displacement, Velocity)
```

```
type AccelerationFunction = State -> Vec
```

```
eulerStep :: AccelerationFunction
           -> Double -> State -> State
```

```
eulerStep a dt (t,r,v) = (t',r',v')
```

```
  where
```

```
    t' = t + dt
```

```
    r' = r ^+^ v ^* dt
```

```
    v' = v ^+^ a(t,r,v) ^* dt
```


Different problems have different acceleration functions

Satellite orbiting the Earth:

$$\vec{F} = -\frac{GMm}{r^2}\hat{r} \qquad \vec{a} = -\frac{GM}{r^2}\hat{r}$$

```
satellite :: AccelerationFunction
```

```
satellite (t,r,v)
```

```
  = 6.67e-11 * 5.98e24 / magnitude r ^ 2 * ^ u
```

```
  where
```

```
    u = negateV r ^/ magnitude r
```

Different problems have different acceleration functions

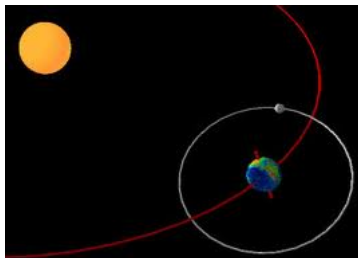
Damped, driven harmonic oscillator:

```
dampedDrivenOsc :: Double -- damping constant  
                -> Double -- drive amplitude  
                -> Double -- drive frequency  
                -> AccelerationFunction
```

```
dampedDrivenOsc beta driveAmp omega (t,r,v)  
  = (forceDamp ^+^ forceDrive ^+^ forceSpring) ^/ mass  
  where  
    forceDamp    = (-beta) *^ v  
    forceDrive   = driveAmp * cos (omega * t) *^ iHat  
    forceSpring  = (-k) *^ r  
    mass         = 1  
    k            = 1 -- spring constant
```

Multiple Particles

```
type SystemState = (Time, [(Displacement, Velocity)])  
type SystemAccFunc = SystemState -> [Vec]
```



Example: Elastic string is modelled as a collection of 100 masses connected by springs.

Structure of Mechanics

1. Choose a *type* to represent the state space for the problem.

```
type State          = (Time, Vec, Vec)
type SystemState = (Time, [(Vec, Vec)])
```

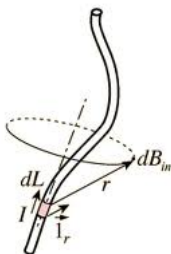
2. Describe how the state changes in time.

```
type AccelerationFunction = State -> Vec
eulerStep :: AccelerationFunction
           -> Double -> State -> State
```

3. Give an initial state for the system.

```
initialState :: State
```

Magnetic Field produced by a Wire



Magnetic field at \vec{r} produced by a current I flowing along a curve C is

$$\vec{B}(\vec{r}) = \frac{\mu_0 I}{4\pi} \int_C \frac{d\vec{l}' \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}. \quad (\text{Biot-Savart law})$$

Data types for curve, scalar field, vector field

```
data Curve
  = Curve { curveFunc      :: Double -> Position
           , startingCurveParam :: Double
           , endingCurveParam  :: Double }
```

```
loopCurve :: Curve
```

```
loopCurve = Curve (\phi -> cyl 1 phi 0) 0 (2*pi)
```

```
type ScalarField = Position -> Double
```

```
type VectorField = Position -> Vec
```

```
type Field v      = Position -> v
```

Integration is a Higher-Order Function

A general purpose “crossed line integral”

$$\int_C \vec{F}(\vec{r}') \times d\vec{l}'$$

-- | Calculates integral of $x dl$ over curve.

`crossedLineIntegral`

```
:: Int           -- ^ number of intervals
-> VectorField  -- ^ vector field
-> Curve        -- ^ curve to integrate over
-> Vec          -- ^ vector result
```

Type signature clarifies purpose

$$\vec{B}(\vec{r}) = \frac{\mu_0 I}{4\pi} \int_C \frac{d\vec{l}' \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} \quad (\text{Biot-Savart law})$$

`bFieldFromLineCurrent`

```
:: Current      -- ^ current (in Amps)
-> Curve        -- ^ geometry of the line current
-> VectorField  -- ^ magnetic field (in Tesla)
```

`bFieldFromLineCurrent i c r`

```
= k *^ crossedLineIntegral 1000 integrand c
```

`where`

```
k = 1e-7 -- mu0 / (4 * pi)
```

```
integrand r' = (-i) *^ d ^/ magnitude d ** 3
```

`where`

```
d = displacement r' r
```


Thanks for Listening!

```
{-# OPTIONS_GHC -Wall #-}
```

```
module Main where
```

```
main :: IO ()
```

```
main = putStrLn "Types and higher-order functions" >>  
      putStrLn "help you learn physics."
```